

FAQ • 02/2016

Operating SINAMICS S120 on a SIMATIC S7-1500 via a Technology Object

TIA Portal V13 SP1 / SIMATIC S7-1500 / SINAMICS S120



https://support.industry.siemens.com/cs/ww/de/view/109482718

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1 Question

How do you operate the SINAMICS S120 drive via a technology object (TO) on a SIMATIC S7-1500?

2 Answer

2.1 Overview

With the SIMATIC S7-1500 there is a simple way of controlling PROFIdrive drives via the integrated technology objects (TOs). This FAQ response takes the example of the SINAMICS S120 drive system to demonstrate this.

2.2 Detailed Description

With the SIMATIC S7-1500 there is a simple way of controlling drives via the integrated technology objects (TOs). Here SIMATIC S7-1500 supports drives with the following types of connection:

- Analog: Control of the drive via an analog speed setpoint of 0..10V.
- PROFIdrive:
 Control of the drive via PROFIdrive telegrams.



Figure 2-1 Selection of the drive connection type

Below we show the example of a SINAMICS S120 connection to the SIMATIC S7-1500 via PROFIdrive profile.

The requirement for using the SINAMICS S120 in the TIA Portal is the complete configuration and commissioning of the drive with the commissioning software SINAMICS MICROMASTER STARTER. You can download the latest version of

the commissioning software as required from the following Siemens Industry Online Support link:

SINAMICS MICROMASTER STARTER
 https://support.industry.siemens.com/cs/en/en/view/26233208

When commissioning the SINAMICS S120 using the commissioning software SINAMICS MICROMASTER STARTER, you must have already selected, configured and optimized the connected motor. Likewise, you must have already defined the desired PROFIdrive telegram for the communication with the SIMATIC S7-1500. The SIMATIC S7-1500 supports the following telegrams for this:

- Telegram 1: Transfer of the speed setpoint in 16-bit resolution.
- Telegram 2: Transfer of the speed setpoint in 32-bit resolution.
- Telegram 3: Additional feedback of the encoder value for controlled positioning.
- Telegram 5:

Feedback of the encoder value and transfer of the error signal and the position controlling gain for utilization of DSC (Dynamic Servo Control) in the drive with a view to improving control quality.

		PZD 1	PZD 2	PZD 3	PZD 4	PZD 5	PZD 6	PZD 7	PZD 8	PZD 9	PZD 10	PZD 11	PZD 12	PZD 13	PZD 14	PZD 15
Telegram 1	CPU ► Drive	STW 1	NSOLL													
	Drive ► CPU	ZSW 1	NIST													
Telegram	CPU ► Drive	STW 1	NSOLL		STW 2											
2	Drive ► CPU	zsw 1	NIST		ZSW 2											
Telegram 3	CPU ► Drive	STW 1	NSOLL		STW 2	G1 STW										
	Drive ► CPU	ZSW 1	NI	NIST ZSW 2		G1 ZSW	e.g. G1 XIST1		e. G1 X	g. IST2						
Telegram 5	CPU ► Drive	STW 1	NSC	DLL	STW 2	G1 STW	XERR		K	PC O						
	Drive ► CPU	ZSW 1	NI	ST	ZSW 2	G1 ZSW	e.g. G1 XIST1		e. G1 X	g. IST2						

Figure 2-2 Telegrams supported by technology objects of S7-1500

Once the SINAMICS S120 is completely commissioned the drive can now also be transferred to the hardware configuration of the TIA Portal. The SINAMICS S120 is already available as an additional field device in the hardware catalog of the TIA Portal and you can incorporate it in the hardware configuration by drag-and-drop.

Hardware catalog		
Options		
✓ Catalog		
<search></search>		irit jirit
🖌 Filter		
Controllers		<u>^</u>
🕨 🛅 HMI		
PC systems		
🕨 🛅 Drives & starters		
Network components		
Detecting & Monitoring		
Distributed I/O		
Field devices		
 Other field devices 		
▼ PROFINET IO		
🔻 🧾 Drives		
TIEMENS AG		
I SINAMICS	\$120 CU310 PN V2.4	
I SINAMICS	\$120 CU310 PN V2.5	
I SINAMICS	\$120 CU310 PN V2.5	
	\$120 CU310 PN V2.5 PN-V2.1	
	S120 CU310 PN V2.5 PN-V2.2	
	\$120 CU310 PN V2.6	
SINAMICS	\$120 CU310 PN V2.6	
SINAMICS	\$120 CU310 PN V2.6 PN-V2.1	
III SINAMICS	\$120 CU310 PN V2.6 PN-V2.2	
SINAMICS	\$120 CU310-2 PN V4.4	
SINAMICS	\$120 CU310-2 PN V4.4	
SINAMICS	S120 CU310-2 PN V4.5	
SINAMICS	\$120 CU310-2 PN V4.5	
SINAMICS	\$120 CU310-2 PN V4.6	
SINAMICS	\$120 CU310-2 PN V4.6	
SINAMICS	S120 CU310-2 PN V4.7	
SINAMICS	\$120/\$150 CBE20 V2.5	
III SINAMICS	\$120/\$150 CBE20 V2.5	
	\$120/\$150 CBE20 V2 5 PN-V2 1	

Figure 2-3 Selection of the SINAMICS S120 in the hardware catalog of the TIA Portal

Then you must assign the inserted drive the same telegram configuration as already stored in the drive via the commissioning software SINAMICS MICROMASTER STARTER.

Figure 2-4 Inserting the telegram configuration in the TIA Portal

dd 📩			D	evice overview						
STR.		^		Y Module	 Rack	Slot	I address	Q address	Туре	
and the second				 SINAMICS-S120-CU310-2PN 	0	0			SINAMICS \$120 CU310-2 PN V4.7	•
Ť				PN-IO	0	0 X150			SINAMICS-S120-CU310-2PN	
=				 DO Control Unit_1 	0	1			DO Control Unit	=
=	1			Module Access Point	0	11			Module Access Point	
			-	without PROFIsafe	0	1 2			without PROFIsafe	
					0	13				
				 DO SERVO_1 	0	2			DO SERVO	
				Module Access Point	0	2 1			Module Access Point	
					0	2 2				
				Standard telegram 3, PZD-5/9; SERVO	0	23	017	09	Standard telegram 3, PZD-5/9; SERVO)
		~			0	24				-
<	-9	. 🗉		٢	^	2			>	Ť

If multiple drives with an extensive telegram configuration are to be integrated in the TIA Portal, the entry below shows you how in the commissioning software SINAMICS MICROMASTER STARTER you generate GSD files for the drives you have configured and integrate them in the TIA Portal:

 SINAMICS G/S: Generating GSDML files for S120, S150, G130, G150 https://support.industry.siemens.com/cs/ww/en/view/92022677 If you use the PROFIdrive telegram 5 for the drive, it is imperative that you connect the SINAMICS S120 isochronous with the SIMATIC S7-1500. Detailed information about this is available in the following entries:

 How Do You Integrate a Drive in the TIA Portal via the Device Master File (GSD)?

https://support.industry.siemens.com/cs/en/en/view/73257075

 Isochronous mode - an example with SIMATIC S7-1500 <u>https://support.industry.siemens.com/cs/en/en/view/109480489</u>

After compilation of the hardware configuration the drive is now completely integrated in the TIA Portal and can be linked to a technology object.

For this you create a corresponding technology object in the SIMATIC S7-1500. For this the S7-1500 provides the following technology objects for linking a drive:

- TO_SpeedAxis Speed axis for pure speed specification on the drive.
- TO_PositioningAxis Positioning axis for position-controlled operation of the drive.
- TO_SynchronousAxis Synchronous axis for connected operation of two axes via a master-slave relationship in which the slave axis must be of the TO_SynchronousAxis type.

This FAQ response takes an example with a positioning axis as technology object.

ld new object					×
Name:					
PositioningAxis					
	Name	Version		Type:	TO_PositioningAxis
	 Motion Control 			Marchan	
- 	 S7-1500 Motion Con 	<u>V2.0</u>		Number:	2
	TO_SpeedAxis	V2.0			🔘 manual
Motion Control	- TO_PositioningAxis	V2.0			automatic
	TO_ExternalEnco	V2.0			Ŭ
	TO_Synchronous	V2.0		Description:	
				The "Positionin	ng axis" (TO_PositioningAxis)
				technology ob	ject maps a physical drive in
				commands to	the drive by means of the user
PID				program with	PLCopen motion control
				instructions.	
.1					
+1					
Counting and					
neasurement					
			•		
			-		
Additional inform	nation				
				_	
Add new and <u>o</u> pen					OK Cancel

Figure 2-5 Selection of the technology object

Now connect the technology object just created to the configured drive by selecting the SINAMICS S120 from the technology object drop-down list box. Make sure however that PROFIdrive is selected as the type of connection for the drive.



Figure 2-6 Connecting the technology object to the drive

Now specify how the encoder of the selected axis is connected to the SIMATIC S7-1500.





To conclude you must transfer the encoder settings from the drive to the technology object.

• •		
PLC	Drive	Power Encoder Motor
Data exchange with the drive Drive telegram: Reference speed: Maximum speed:	DP_TEL3_STANDARD 3000.0 1/min 3000.0 1/min Invert drive direction	 Device configuration The specification of the drive speed is a percentage of the reference speed in the range -200% to +200%.
Data exchange with encoder Encoder telegram: Encoder type: Steps per revolution: Fine resolution Bits in incr. actual value (GN	DP_TEL3_STANDARD Rotary incremental 2048 L_XIST1): 11 bits	The parameters of the encoder telegram must correspond to the data in the device configuration.
	Invert encoder direction	

Figure 2-8 Making the encoder settings on the technology object

The settings can be taken from the following parameters from the commissioning software SINAMICS MICROMASTER STARTER:

Parameter designation TIA Portal	Parameter STARTER	Sample value in the figure		
Data exchange with the drive		-		
Drive telegram	p2079	DP_TEL3_STANDARD		
Reference speed	p2000	3000.0		
Maximum speed	p311[0]	3000.0		
Data exchange with encoder				
Encoder telegram	p2079	DP_TEL3_STANDARD		
Encoder type	p400	Rotary incremental		
Steps per revolution	p408[0] or r979[2]	2048		
Bits in incr. actual value (GN_XIST1)	p4108[0] or r979[3]	11		
Invert encoder direction	p410[0]	No		

Now you can control the drive via the PLCopen functions of the SIMATIC S7-1500 using the technology object.

2.3 Further Information

More information about using the technology objects of the SIMATIC S7-1500 is also available in the following entries:

- SIMATIC S7-1500: Introduction to the functions and configuration and programming of the S7-1500 controller family in the form of a "Getting Started" https://support.industry.siemens.com/cs/en/en/view/78027451
- SINAMICS G: Control of speed of a G110M / G120 (Startdrive) with S7-1200 (TO) via PROFINET or PROFIBUS DP with Safety Integrated (via terminal) and HMI <u>https://support.industry.siemens.com/cs/en/en/view/78788716</u>
- SINAMICS G: Positioning of a G110M/G120 (Startdrive) with S7-1500 (TO) via PROFINET/PROFIBUS with Safety Integrated and HMI <u>https://support.industry.siemens.com/cs/en/en/view/81666970</u>