

SINAMICSG120 / G120C / G120D, G110M / ET 200pro FC-2

Product information, FW 4.7 SP10

04/2018

For Firmware version 4.7 SP10, the list manuals of version V4.7 SP9 (Edition 09/2017) are valid for the products SINAMICS G120 CU240B/E-2, CU250S-2, G120C, G120D, G110M and SIMATIC ET 200pro.

The minor changes can be found in this product information.

A new edition (04/2018) has been issued for G120 CU230P-2.

Valid list manuals for version V4.7 SP10:

Product	Control Units	List manual short name	Valid list manual for version V4.7 SP10
SINAMICS G120	CU230P-2	LH09	Version V4.7 SP10, (04/2018)
	CU240B/E-2	LH11	Version V4.7 SP9, (09/2017)
	CU250S-2	LH15	Version V4.7 SP9, (09/2017)
SINAMICS G120C		LH13	Version V4.7 SP9, (09/2017)
SINAMICS G120D	CU240D-2	LH14	Version V4.7 SP9, (09/2017)
	CU250D-2		
SINAMICS G110M		LH16	Version V4.7 SP9, (09/2017)
SIMATIC ET 200pro		LH20	Version V4.7 SP9, (09/2017)

The parameter list contains the following changes

New parameter r7844:

r7844[0...2] Memory card/device memory firmware version/ Sp_karte/Ger_sp FW

Description: Displays the version of the firmware stored on the memory medium of the drive device.

Depending on the drive device being used, the memory medium is a memory card, or an internal non-volatile

device memory.

Index: [0] = Internal [1] = External

[2] = Parameter backup

Note: For index 0:

Displays the internal firmware version (e.g. 04402315).

This firmware version is the version of the memory card/device memory and not the CU firmware (r0018),

however, normally they have the same versions.

For index 1:

Displays the external firmware version (e.g. $04040000 \rightarrow 4.4$, $04071001 \rightarrow V4.7$ SP10 HF1).

For automation systems with SINAMICS Integrated, this is the runtime version of the automation system.

For index 2:

Displays the internal firmware version of the parameter backup.

With this CU firmware version, the parameter backup was saved, which was used when powering up.

Expansions for BACnet MS/TP and Modbus RTU:

p2020:

For p2030 = 5 (BACnet MS/TP) the following applies:

Possible values/factory setting: (6, 7, 8, 10) / 8

p2024:

Factory setting p2024[0] = 6000

p2025

Factory settings p2025[1] = 5, p2025[3] = 32

p2030

Change to the designation for value: 5: BACnet changed to BACnet: MS/TP

p2040

Factory setting 1000

Note added:

For p2030 = 2 (Modbus RTU) or p2030 = 5 (BACnet MS/TP) the following deviation applies:

Factory setting: 10000

r2057

The parameter is now available for the following fieldbuses:

PROFIBUS, CAN, USS, Modbus RTU, BACnet MS/TP, P1

p7610[0...78]:

The description was expanded to include the following sentence:

The object name is preassigned with device name and serial number the first time that the system runs up, e.g.: "SINAMICS G120 CU230P-2 HVAC - XAB812-005806"

New bit in p1780 for PM230 Power Module

Bit 8: Deselect preliminary measurement of inductance for pole position identification 1 signal = yes, 0 signal = no, factory setting = 0

Change to parameter p1800

The following dependency was added:

Minimum pulse frequency: p1800 >= 12 * p1082 * r0313 / 60

The following note was added:

The pulse frequency cannot be changed when the motor data identification is activated.

New value in p0595, p11026, p11126, p11226

48: kg/cm²

New fault F30068

F30068 power unit: Undertemperature inverter heatsink

Message class: power electronics faulted (5)

Response: OFF2

Acknowledgment: IMMEDIATELY

Cause: The actual inverter heat sink temperature is below the permissible minimum value.

Possible causes:

- the power unit is being operated at an ambient temperature that lies below the permissible range.

- the temperature sensor evaluation is defective.

Fault value (r0949, interpret as decimal): Inverter heat sink temperature [0.1 °C].

Remedy: - ensure that higher ambient temperatures prevail.

- replace the power unit.

New fault values in fault F01682

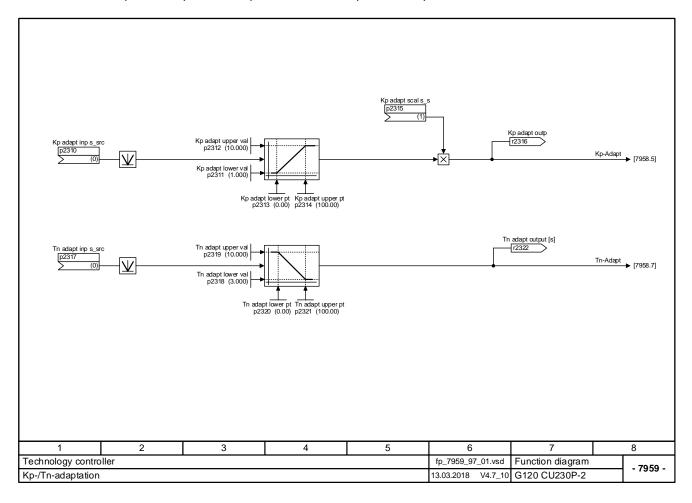
56: For "GX" Power Modules, encoderless monitoring functions are not supported. 9586: Set value of p9586/p9386 is greater than the supported maximum value.

9588: Set value of p9588/p9388 is greater than the supported maximum value.

9589: Set value of p9589/p9389 is greater than the supported maximum value.

Adapted function diagram 7959 for G120 CU230P-2 and CU240B/E-2

The graphic for the Tn adaptation was adapted as the reference points were not correctly specified. The signal characteristic in the Tn adaptation was corrected from rising to falling, so that now the correct reference points for p2319 and p2320, as well as p2318 and p2321 are visible.



Supplement to function diagrams [2475] and [2479] for G120 CU250S-2 and CU250D-2

Up until now, function diagrams for STW1 [2475] and ZSW1 [2479] in the positioning mode were missing in the documentation. These are required if the basic positioner (EPOS) and telegram 7, 9, 110 or 111 are used.

-	argets for STW1 (positioning mode, p0108.4	-,					1	
Signal	Meaning		Interconnection parameters	[Function diagram] internal control word	[Function diagram] signal target	Inverted		
STW1.0	= ON (pulses can be enabled) 0 = OFF1 (braking with ramp-function generator, then pulse suppress	p0840[0] = r2090.0	[2501.3]	Sequence control	-			
STW1.1	1 = No OFF2 (enable is possible) 0 = OFF2 (immediate pulse suppression and switching on inhibited)	p0844[0] = r2090.1	[2501.3]	Sequence control	-			
STW1.2	1 = No OFF3 (enable is possible) 0 = OFF3 (braking with the OFF3 ramp p1135, then pulse suppression	p0848[0] = r2090.2	[2501.3]	Sequence control	-			
STW1.3	1 = Enable operation (pulses can be enabled) 0 = Inhibit operation (suppress pulses)	p0852[0] = r2090.3	[2501.3]	Sequence control				
STW1.4	1 = Do not reject traversing task 0 = Reject traversing task	p2641 = r2090.4	-	[3616.5], [3625]				
STW1.5	1 = No intermediate stop 0 = Intermediate stop	p2640 = r2090.5		[3616.5], [3625]	-			
STW1.6	= Activate traversing task	<3> p2631 = r2090.6 p2650 = r2090.6	-	[3616.1], [3620.1], [3625]	-			
STW1.7	= Acknowledge faults	= Acknowledge faults			[8060]	-		
STW1.8	1 = Jog 1 signal source	1 = Jog 1 signal source			[3610.1], [3625]	-		
STW1.9	1 = Jog 2 signal source	p2590 = r2090.9	-	[3610.1], [3625]	-			
STW1.10	1 = Control via PLC	p0854[0] = r2090.10	[2501.3]	[2501]	-			
STW1.11	1 = Start referencing 1 = Stop referencing		p2595 = r2090.11		[3612.1], [3625]	-		
STW1.12	Reserved		-			-		
STW1.13	= External block change		p2633 = r2090.13	-	[3615]	-		
STW1.14	Reserved		-	-	-	-		
STW1.15	Reserved		-		-	-		
	elegrams 7, 9, 110, 111. STW1 must be set to ensure that the drive accepts the process data.		<3> The i	nterconnection p2649 = 0 is m	nade additionally only in Teleg	ram 7, 9 and 1	10.	
1	2 3	4	5	6	7		8	
ROFIdriv	e (PROFIBUS/PROFINET), EtherNet/IP			fp_2475_97_55.vsd	Function diagram	n diagram		
OFIdriv	OFIdrive - STW1 control word interconnection (p0108.4 = 1)				14.03.2018 V4.7 10 G120 CU250S-2 DP/PN			

ignai s	ources	for ZSW1 (position	ning mode, pulus	4 = 1)				<1>	1
Signal			Meaning		Interconnection parameters	[Function diagram] internal control word	[Function diagram] signal source	Inverted	
ZSW1.0	1 = Ready	y for switch on			p2080[0] = r0899.0	[2503.7]	Sequence control	-	
ZSW1.1	1 = Ready (DC link loaded, pulses inhibited)			p2080[1] = r0899.1	[2503.7]	Sequence control	-		
ZSW1.2	1 = Operation enabled (drive follows n_set)				p2080[2] = r0899.2	[2503.7]	Sequence control	-	
ZSW1.3	1 = Fault present			p2080[3] = r2139.3	[2548.7]	[8060]			
ZSW1.4	1 = No co	ast down active (OFF2 inactive	е)		p2080[4] = r0899.4	[2503.7]	Sequence control	-	
ZSW1.5	1 = No Qu	uick stop active (OFF3 inactive))		p2080[5] = r0899.5	[2503.7]	Sequence control	-	
ZSW1.6	1 = Switch	hing on inhibited active			p2080[6] = r0899.6	[2503.7]	Sequence control	-	
ZSW1.7	1 = Alarm	present			p2080[7] = r2139.7	[2548.7]	[8065]	-	
ZSW1.8	1 = Follow	ving error within tolerance			p2080[8] = r2684.8	[3646.7]	[4025.8]	-	
ZSW1.9	1 = Contro	ol requested		<2>	p2080[9] = r0899.9	[2503.7]	[2503]	-	
ZSW1.10	1 = Targe	t position reached			p2080[10] = r2684.10	[3646.7]	[3625], [4020.8]		
ZSW1.11	1 = Refer	ence point set			p2080[11] = r2684.11	[3646.7]	[3612.7], [3614.7]	-	
ZSW1.12	_ = Ackno	owledgment traversing block a	ctivated		p2080[12] = r2684.12	[3646.7]	[3616.6], [3620.8]	-	
ZSW1.13	1 = Setpo	int available			p2080[13] = r2683.2	[3645.7]	[3635.6]	,	
ZSW1.14	1 = Axis is	s accelerating		<3>	p2080[14] =r2684.4	[3646.7]	[3635.6]	-	
ZSW1.15	1 = Axis is	s decelerating		<3>	p2080[15] = r2684.5	[3646.7]	[3635.6]	-	
1> Used in t 2> The drive		9, 110, 111. ady to accept data.			<3> Only	for telegram 111.			
1		2	3	4	5	6	7	{	8
ROFIdriv	e (PRO	FIBUS/PROFINET)	, EtherNet/IP	•		fp_2479_97_55.vsd	Function diagram		24-
ROFIdriv	e - ZSW1 status word interconnection (p0108.4 = 1)				14.03.2018 V4.7_10 G120 CU250S-2 DP/PN			- 247	

Supplement to footnote <1> on function diagram [2444] for G120 CU250S-2 and CU250D-2

	Drive Data Set selection DDS bit 0			parameters	internal control word	signal target	Inverted
STW2.1 STW2.2	Drive Data Set selection DDS bit 0			p0820[0] = r2093.0	-	[8565]	-
STW2.2	Drive Data Set selection DDS bit 1			p0821[0] = r2093.1	-	[8565]	-
1	Reserved			-	-	-	-
STW2.3	Reserved			-	-	-	-
STW2.4	Reserved	-	-	-	-		
STW2.5	Reserved		-	-	-	-	
STW2.6	Reserved			-	-	-	-
STW2.7	1 = Parking axis is selected			p0897 = r2093.7	-	-	-
STW2.8	1 = Traverse to fixed endstop active		<1>	p1545[0] = r2093.8	[2520.2]	[8012]	-
STW2.9	Reserved			-	-	-	-
STW2.10	Reserved			-	-	-	-
STW2.11	Reserved			-	-	-	-
STW2.12	Master sign-of-life, bit 0			p2045 = r2050[3]		[2410]	-
STW2.13	Master sign-of-life, bit 1						
STW2.14	Master sign-of-life, bit 2						
STW2.15	Master sign-of-life, bit 3						
Not for tele	egrams 9, 110 and 111.						•
1	2	3	4	5	6	7	