SIRIUS 3RA6 Reversing Starter with AS-i Mounting Module Local Safety Shutdown at SIL 1 acc. to IEC 62061 / PL c acc. to EN ISO 13849-1:2006

**SIRIUS** 

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#### Question

How can I use the local inputs of the AS-i mounting module of the 3RA6 reversing starter?

What safety category can be achieved with the local inputs of the AS-i mounting module?

#### **Answer**

One example is the monitoring of the limit position of a conveyor belt.

SIL 1 according to IEC 62061 resp. PL c according to EN ISO 13849-1:2006 (in the following ISO 13849-1) can be achieved.

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### 1 Introduction

Based on the functional safety standards IEC 62061 and ISO 13849-1 it is possible to perform a qualitative and quantitative assessment of safety functions with non-safety-related (standard) components.

Examples of such non-safety-related (standard) components are the switching and protection devices of the SIRIUS Innovation series. These devices are frequently used in applications aimed at the protection of assets.

This FAQ describes how two position switches with a positively-opening contact can be monitored by using the local inputs of the AS-i mounting module, so as to initiate the safe shutdown of the 3RA6 at level SIL 1 according to IEC 62061 or PL c according ISO 13849-1 or category 2 according to EN 954-1. Operation of the position switch will cause the 3RA6 compact feeder to disconnect. In this example, a drive unit will be shut down.

The machine under consideration uses a drive to move a lifting mechanism to two defined conveyor levels. The drive is controlled by means of a compact feeder type RA62 (reversing starter). The pick-up and place-down positions of the lifting unit are monitored in automatic mode with the help of proximity switches. These proximity switches are registered and analyzed by the SIMATIC controller. For the purpose of servicing and maintenance, the stop positions effective in automatic mode can be exceeded. In the setup mode, however, the upper and lower limit positions are monitored by mechanical position switches for the reason of machine safety. This disconnection at the end position of the lifting drive is then effected through direct analysis of the position switches at the local inputs of the AS-i mounting module. This direct shutdown becomes also effective when an incident occurs (e.g. failure of one proximity switch).

#### 1.1 Notes regarding the S7 program

- The feedback information from the motor starter profile is analyzed non-safetyrelated and at cyclic intervals via AS-i in the SIMATIC S7 CPU.
- Due to the standardized process data of the motor starter profile for an AS-i slave, the upper and lower end positions of the operated position switches must be determined through logic analysis in SIMATIC.
- After analysis via the AS-i bus, the output for the deactivated direction of movement must be reset in the controller.
- Accordingly, the output for the opposite direction can be reset in the controller.
- Logic assignment of process data and process images:

Compact feeder	Inputs				Outputs	
status	D0	D1	D2	D3	D0	D1
	Compact feeder ready for operation	Motor ON	Group fault	General warning	Motor "direction of rotation 1"	Motor "direction of rotation 2"
Normal mode	X					
AUX Power			X			
deactivated,						
undervoltage,						
overvoltage						
Output 1 (Motor ON)	X	X			X	
set via master						
Output 1 (Motor ON)	X	X				X
set via master						
Overload	X		X	X		
Limit position switch open	Х		X			

#### Note

The upper and lower end position of the operated position switches must be determined through logic analysis of the process image in SIMATIC, because:

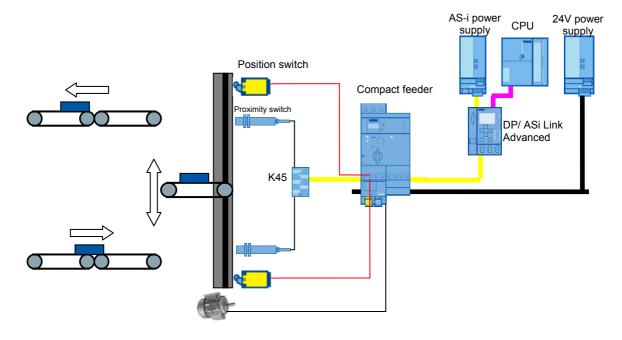
- the image is identical for both motor rotation directions
- the image is identical for the "open" states of both limit position switches.

#### 1.2 Customer benefits

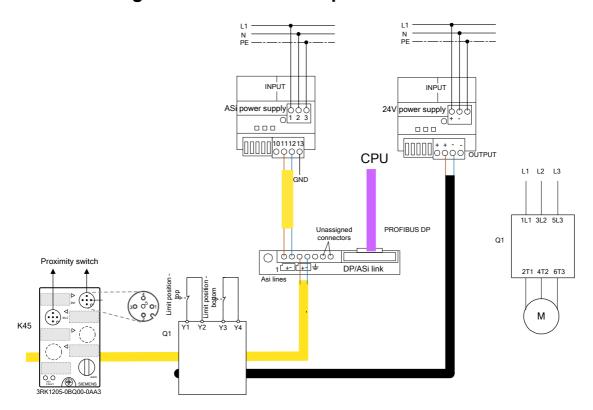
- The very simple wire connections secure machine protection for 2 limit positions
- Quick disconnection independently of bus and PLC cycle times
- Standstill in compliance with stop category 0 according to EN60204-1
- Saves time and money through quick installation and commissioning and very easy wiring
- Extremely durable, maintenance-free, robust and reliable
- Easy to retrofit and locally restricted "safety control range"

# 2 Setup and Wiring

# 2.1 Hardware setup – overview



# 2.2 Wiring of the hardware components



# 3 Evaluation according to IEC 62061 and ISO 13849-1

## 3.1 Safety functions

Further considerations are based on the following safety function:

safety function	
SF 1	The motor must be switched off
	when the position switch for clockwise rotation is actuated.
SF 2	The motor must be switched off
	when the position switch for counterclockwise rotation is actuated.

The safety function listed above is evaluated below according to the two standards IEC 62061 and ISO 13849-1.

The same components are involved in safety functions 1 and 2. Therefore, they are only evaluated once in this example.

# 3.2 Evaluation according to IEC 62061

Parameters for the calculation of  $PFH_D$  for

"Detection" (position switch) and "Responding" (Compact Feeder)

Detection (position switch) and Responding (Compact Feeder)				
Parameter	Value	Reason	Definition	
B10 position switch Compact Feeder	1 * 10 <sup>6</sup> 3 * 10 <sup>6</sup>	Manufacturer specifications		
Ratio of Dangerous Failures position switch Compact Feeder	0,2 0,5	Manufacturer specifications (20%) (50%)	Siemens	
T1 Useful life time	175.200h (20Jahre)	Manufacturer specifications		
C Number of actuations of position switch  Number of actuations of Compact Feeder	0,125/ h 10 / h	Assumptions: Actuated once per shift, every 8 hours. Actuation may take place every day of the year (365 days). Actuated 10 times per hour,.	User	
DC Diagnostic Coverage	0 (0%)	No fault reaction is initiated. (Worst case).		

#### **Evaluation Parameters**

		Definition
Fault exclusion	based on the use of the local input for safety related switching off at 3RA6	Siemens

Summary

		IEC 620	61	
		SIL CL		PFH <sub>D</sub>
Detect 1		Hardware Fault Tolerance: HFT = 0 Ratio of Dangerous Failures: SFF = 0 (0%) Use of proven components	2.50 * 10 <sup>-09</sup>	Architecture: Basic subsystem architecture A
Evaluate Fault exclusion		Fault exclusion		
Respond	1	Hardware Fault Tolerance: HFT = 0 Safe Failure Fraction: SFF = 0 (0%) Use of proven components	1.66 * 10 <sup>-07</sup>	Architecture: Basic subsystem architecture A
Result	1 SIL CL of all tasks of the supplementary safety function is at least 1. PFH <sub>D</sub> (=1.69 *10 <sup>-07</sup> ) of the entire supplementary safety function fulfill requirements of SIL1.			nction is at least 1. afety function fulfills the

# 3.3 Evaluation according to ISO 13849-1

Parameters for the calculation of MTTFd for

"Detection" (position switch) and "Responding" (Compact Feeder)

Parameter	Value	Reason	Definition
B10		Manufacturer specifications	
position switch	1 * 10 <sup>6</sup>		Siemens
Compact Feeder	3 * 10 <sup>6</sup>		
Ratio of Dangerous Failures		Manufacturer specifications	
position switch	0,2	(20%)	
Compact Feeder	0,5	(50%)	
d <sub>op</sub>	365 days per	Assumptions:	
Mean operating time in days per year	year	Actuation takes place every	
h <sub>op</sub>	24 hours per	day of the year	
Mean operating time in hours per day	day	(365 days).	
t <sub>cycle</sub>			User
Mean time between the start of two		Assumptions:	
consecutive cycles of the component			
position switch	8 h/cycle	There is an interval of 8	
		hours between each	
		actuation (one shift).	
Compact Feeder	0.1 h/cycle	The Compact Starter is	
		operated 10 times per hour.	

Interim results (are identical in this example for position switch and compact Feeder):

Interim result	ts	Reason
MTTF <sub>d</sub>	high	MTTF <sub>d</sub> ≥30 years
DC	none	DC=0%
Measures against CCF	not relevant	
Category	1	System behavior: A single fault can result in the loss of the safety function

#### **Evaluation of Parameters**

		Festlegung
Fault exclusion	based on the use of the local input for safety related switching off at 3RA6	Siemens

#### Summary

		ISO 13849-1		
	PL	Probability of dangerous failure per hour (PFH <sub>D</sub> )		
Detect	С	1,14*10 <sup>-06</sup> (from Annex K; see note)		
Evaluate		Fault exclusion		
Respond	С	1,14*10 <sup>-06</sup> (from Annex K; see note)		
Result	С	PL of all tasks of the supplementary safety function is at least c.		

Note: The MTTF $_{\mbox{\scriptsize d}}$  for each channel is limited to max. 100 years!

## 3.4 Summary

	IEC 62061		ISO 13849-1		
	SIL CL	PFH <sub>D</sub>	PL	Probability of dangerous failure per hour (PFH <sub>D</sub> )	
Detect	1	1,2 * 10 <sup>-09</sup>	С	1,14*10 <sup>-06</sup>	
Evaluate	Fault exclusion			Fault exclusion	
Respond	1	4,5 * 10 <sup>-10</sup>	С	1,14*10 <sup>-06</sup>	

Result	SIL1	PL c

## 4 Literature

#### 4.1 Literature

The following list is by no means complete and only provides a selection of related references.

Table 4-1

	Source	Title
\1\	Brochure	Functional safety of Machines and Systems  – Easy Implementation of the European Machinery Directive  (Order no.: E20001-A230-M103-V1)
\2\	Technical book	Patrick Gehlen Funktionale Sicherheit von Maschinen und Anlagen Umsetzung der Europäischen Maschinenrichtlinie in der Praxis (Publicis Corporate Publishing, ISBN: 978-3-89578-366-1)

## 4.2 Internet links

The following list is by no means complete and only provides a selection of useful information.

Table 4-2

	Subject	Title
\1\	Reference to this document	http://support.automation.siemens.com/WW/view/en/45147736
\2\	Siemens I IA/DT Customer Support	http://support.automation.siemens.com
/3/	Safety Evaluation Tool	http://www.siemens.de/safety-evaluation-tool
\4\	Safety Integrated	http://www.siemens.com/safety-integrated